

# On Validity of Extreme Value Theory-Based Parametric Models for Out-of-Distribution Detection

Tomasz Walkowiak<sup>[0000-0002-7749-4251]</sup>, Kamil Szyc<sup>[0000-0001-6723-271X]</sup>, and  
Henryk Maciejewski<sup>[0000-0002-8405-9987]</sup>

Wroclaw University of Science and Technology  
{[tomasz.walkowiak](mailto:tomasz.walkowiak@pwr.edu.pl),[kamil.szyc](mailto:kamil.szyc@pwr.edu.pl),[henryk.maciejewski](mailto:henryk.maciejewski@pwr.edu.pl)}@pwr.edu.pl

**Abstract.** Open-set classifiers need to be able to recognize inputs that are unlike the training or known data. As this problem, known as out-of-distribution (OoD) detection, is non-trivial, a number of methods to do this have been proposed. These methods are mostly heuristic, with no clear consensus in the literature as to which should be used in specific OoD detection tasks. In this work, we focus on a recently proposed, yet popular, Extreme Value Machine (EVM) algorithm. The method is unique as it uses parametric models of class inclusion, justified by the Extreme Value Theory, and as such is deemed superior to heuristic methods. However, we demonstrated a number of open-set text and image recognition tasks, in which the EVM was outperformed by simple heuristics. We explain this by showing that the parametric (Weibull) model in EVM is not appropriate in many real datasets, which is due to unsatisfied assumptions of the Extreme Value Theorem. Hence we argue that the EVM should be considered another heuristic method.

**Keywords:** Open-set classification · Out-of-distribution detection · Extreme Value Machine · Extreme Value Theory.

## 1 Introduction

Machine learning systems deployed for real-world recognition tasks often have to deal with data that come from categories unseen during training. This occurs especially in image or text recognition, where it is usually infeasible to collect training examples that correspond to all categories which can be encountered at prediction time. Hence it is important that classifiers can detect such examples as unrecognized and not silently assign them to one of the known classes. However, most state-of-the-art models for image recognition operate as closed-set classifiers, i.e., they tend to assign any example to some of the known classes. An illustration of such behavior by the well-known ResNet model is shown in Fig. 1. Such misclassification errors limit adoption of closed-set models in problems where new categories emerge over time (incremental learning problems) or can lead to accidents in safety-critical computer vision applications, which is a crucial concern in AI Safety [1].



Fig. 1: Images of unknown class (Ligature, Highway, not available in training data) recognized by the ResNet-50 model as a known class (Ligature recognized as Jellyfish, Highway recognized as Dam). Examples from [12]

To deal with this problem, several methods have been proposed to recognize when inputs to classifiers are unlike the training examples. In different studies, such inputs are referred to as anomalous, outliers, or out-of-distribution (OoD) examples with regard to the training data. Classifiers that incorporate such detection methods are known as open-set classifiers. A recent comprehensive survey of open-set recognition methods is given in [6]. Closed-set classifiers fail to reject OoD examples, as they approximate posterior probabilities  $P(c_i|x)$  for an input sample  $x$ , where  $c_i \in \{c_1, c_2, \dots, c_M\}$  are the categories known in training data and assign any sample to the class maximizing  $P(c_i|x)$ . Open-set classifiers attempt to reject unrecognized inputs that are reasonably far from known data. This is, broadly, done by constructing decision boundaries based on distributions of training data or by building abating probability models, where the probability of class membership decreases as observations move from training/known data.

An example of the former approach is the '1-vs-set' model proposed by [23], and examples of the latter are W-SVM [22], or PI-SVM (probability-of-inclusion SVM) by [13] (all these methods are open-set versions of the SVM model). Junior et al. [14] proposed an open-set version of the Nearest-Neighbours classifier, with a threshold on class similarity scores used to realize the rejection option. Bendale and Bould [2] proposed an open-set version the nearest-class-mean model [17], with rejection based on the thresholded Mahalanobis distance, see also [15]. Specific models for open-set recognition with deep CNNs include the Openmax [3] and OoD methods with outlier-exposure [10, 9], which rely on the observation that OoD differs in terms of the distribution of softmax probabilities as compared with known (in-distribution) examples.

In contrast to all these methods, which can be seen as heuristic procedures, with no theoretical justification, Rudd et al. [20] proposed a theoretically sound classifier - the Extreme Value Machine (EVM). Its parametric model of the

probability of inclusion uses the Weibull distribution, which is justified by the Extreme Value Theory. The authors claim that this leads to the superior performance of EVM on some open-set benchmark studies reported as compared to heuristic methods.

The motivation of this research comes from the observation we made that for a number of datasets in text or image recognition the EVM is surpassed by simpler, heuristic models. The main contributions of this work are the following. We analyzed Extreme Value Theory assumptions, which justify the adoption of the Weibull distribution by the EVM method. We showed that these assumptions often do not hold in real recognition problems and illustrated this in a number of text and image classification studies. We empirically compared the EVM with simple OoD detection methods based on the LOF (Local Outlier Factor) and explained what properties of the training data lead to low performance of the EVM. We conclude that the theoretical soundness of EVM in many real-life studies can be questioned, and hence the method should be considered another heuristic procedure.

The paper is organized as follows. In section 2, we explain how open-set classifiers perform out of distribution detection using a probability of inclusion-based and density-based methods. Then we provide details on the EVM (probability of inclusion-based) and the LOF (density-based), which we later use in the comparative study. We also provide OoD evaluation metrics. In section 3 we report results of the numerical study comparing EVM with LOF on both text and image data and provide results of goodness-of-fit tests, which show that the EVM Weibull model is not appropriate. We discuss this concerning the EVT assumptions. Finally, we discuss the type of inter-class separation which most likely leads to the low performance of the EVM.

## 2 Methods

### 2.1 Out of Distribution Detection

In order to realize open-set recognition, classifiers must be able to reject as unrecognized the samples which are out-of distribution with regard to the training data of known classes. This allows reducing the open-space risk [23], i.e. misclassification of these OoD samples by assigning them to one of the known classes.

The key difference between open-set classifiers is how the rejection option is implemented.

A commonly used approach to reduce the open-space risk is to implement the *probability of inclusion* model. An input sample  $x$  is then classified as  $c_i = \arg \max_{c \in C} P(c|x)$  providing  $P(c_i|x) > \delta$ , and labelled as unrecognized otherwise. The models of the probability of class inclusion attempt to model  $P(c_i|x)$  as a decreasing function of the distance between  $x$  and the training data  $X_i$  pertaining to class  $c_i$ . Such models are referred to as compact abating probability (CAP) models [22]. The Extreme Value Machine which is the focus of this work is based on this idea; in section 2.3 we explain how EVM constructs the CAP model for  $P(c_i|x)$ .

Another approach is realized by distance-based methods, where rejection is done by directly using distance to known data. An input sample  $x$  is classified as  $c_i = \arg \max_{c \in C} P(c|x)$  providing  $d(x, X_i) < \delta$ , where  $d(x, X_i)$  is some measure of distance between  $x$  and the known training data  $X_i$  pertaining to class  $c_i$ . For  $d(x, X_i) \geq \delta$ ,  $x$  is unrecognized. This idea is implemented e.g. by the open-set version of the nearest class mean classifier [2, 17], where  $d(x, X_i)$  is calculated as Mahalanobis distance.

Density-based methods can be seen as conceptually related to the distance-based methods, however the measure  $d(x, X_i)$  used to realize rejection of OoD samples is calculated as some measure of outlierness of  $x$  with regard to the known data  $X_i$ . This can be based on the density or the outlierness factor such as the Local Outlier Factor (LOF) [4]. The latter is used in the empirical study as an alternative method compared to the Extreme Value Machine.

## 2.2 Local Outlier Factor

The Local Outlier Factor [4] is based on an analysis of the local density of points. It works by calculating the so-called *local reachability distance*, defined as an average distance between a given point, its neighbors, and their neighbors. The relative density of a point against its neighbors is used to indicate the degree of the object being an OoD. The local outlier factor is formally defined as the average of the ratio of the local reachability of an object to its k-nearest neighbors. If the LOF value for a given point is larger than some threshold, the point is assumed to be OoD. In the case of the open set classification problem, the LOF threshold could be calculated based on the assumption that the training data include a given portion of outliers (called contamination in code <sup>1</sup>).

## 2.3 Extreme Value Machine

Extreme Value Machine constructs a compact abating probability model of  $P(c_i|x)$  that  $x$  belongs to  $c_i$ . This popular model is justified by the Extreme Value Theory, and as such, deemed superior by the authors as compared with heuristic models.

Technically, to construct the CAP model for a class  $c_i \in C = \{c_1, c_2, \dots, c_M\}$ , we create the radial inclusion function for each point  $x_i \in X_i$ , where  $X_i$  represents the training data for class  $c_i$ . Given a fixed point  $x_i \in X_i$ ,  $\tau$  closest training examples from classes other than  $c_i$  are selected, denoted here as  $\{t_1, \dots, t_\tau\}$ , and the margin distances from  $x_i$  to these examples are calculated as

$$m_{ij} = \frac{\|x_i - t_j\|}{2}, \quad j = 1, \dots, \tau \quad (1)$$

Then the parametric model of the margin distance from  $x_i$  is estimated by fitting the Weibull distribution to the data  $\{m_{i1}, m_{i2}, \dots, m_{i\tau}\}$ . This step is justified by the authors by the Extreme Value Theory, and is later analyzed

<sup>1</sup> <http://scikit-learn.org/stable/modules/generated/sklearn.neighbors.LocalOutlierFactor.html>

in terms of validity of the underlying assumptions in section 3.3. The fitted Weibull model is described by the scale  $\lambda_i$  and shape  $\kappa_i$  parameters, and hence the Weibull survival function ( $1-CDF$ ) is postulated as the radial class inclusion function:

$$\Psi(x_i, x) = e^{-\left(\frac{\|x_i - x\|}{\lambda_i}\right)^{\kappa_i}} \quad (2)$$

This can be interpreted as the CAP model of the decreasing probability of inclusion of the sample  $x$  in the class represented by training example  $x_i$ .

Given this model, the open-set classification of an input  $x$  is done as follows. The probability that  $x$  is associated with the class  $c_i$  is estimated as  $\hat{P}(c_i|x) = \Psi(x_j, x)$ , where  $x_j = \arg \max_{x_k \in X_i} \Psi(x_k, x)$  (ie.  $x_j$  is the training example in  $X_i$  closest to  $x$ ). Finally, the open-set classification of  $x$  is done as  $c_i = \arg \max_{c \in C} \hat{P}(c|x)$  if  $\hat{P}(c_i|x) > \delta$ , and  $x$  is considered unknown otherwise.

### Remarks on the Extreme Value Machine Implementation

It should be noticed that the ‘official’ implementation of the EVM<sup>2</sup> uses the libMR<sup>3</sup> library for the Weibull model fitting (libMR is provided by the authors of [24]). Given the sample  $\{m_{i1}, m_{i2}, \dots, m_{i\tau}\}$ , libMR first performs linear transformation:  $\eta_{ij} = -m_{ij} - \max\{m_{i1}, m_{i2}, \dots, m_{i\tau}\} + 1$ ,  $j = 1, \dots, \tau$ , and then returns the parameters  $(\lambda_i, \kappa_i)$  of the Weibull model fitted to  $\{\eta_{i1}, \eta_{i2}, \dots, \eta_{i\tau}\}$ . The parameters  $(\lambda_i, \kappa_i)$  are used in Eq. 2.

In the empirical study in Section 3, we verify the goodness of this fit and show that in all the datasets considered the Weibull model is *not* appropriate for  $\{m_{i1}, m_{i2}, \dots, m_{i\tau}\}$  (the original margin distances) and for  $\{\eta_{i1}, \eta_{i2}, \dots, \eta_{i\tau}\}$  (the transformed margin distances).

#### 2.4 OoD Evaluation Metric

In the next section, we want to empirically compare the performance of the EVM and LOF methods in the task of OoD detection. In the evaluation of OoD detection algorithms, we follow the approach used in [11]. OoD detection is treated as binary classification, with the OoD examples defined as the positive class and the in-distribution examples as the negative class. As the OoD detection quality metric we used the area under the receiver operating characteristic curve (AUROC). It could be used since EVM and LOF (and other OoD methods, Section 2.1) use a rejection threshold value which affects the false positive and true negative rates. Technically, the ROC curve shows the False Positive Rate (FPR) on the x-axis and the True Positive Rate (TPR) on the y-axis across multiple thresholds. In the OoD problem, the FPR measures the fraction of in-distribution examples that are misclassified as outliers. The TPR measures the fraction of OoD examples that are correctly labeled as outliers.

<sup>2</sup> <https://github.com/EMRResearch/ExtremeValueMachine>

<sup>3</sup> <https://github.com/Vastlab/libMR>

The performed experiments data were divided into three data sets: training, testing, and outlier one. The first two are classical data sets used in closed-set classification and represent in-distribution data. The training data set was used to build OoD models, where test and outlier ones (as a negative and positive class) are used to evaluate OoD algorithms. In performed experiments, the number of outliers was set to be equal to the size of the test data. It could be noticed that in the presented approach, OoD detection algorithms have no knowledge about OoD world. They built their models based on in-distribution data only.

### 3 Computational Experiments

In this section, we empirically compare the EVM and LOF methods in the task of OoD in image classification and text documents classification. Since results of this study (Section 3.2) show that the theoretically-justified EMV can be outperformed by a heuristic procedure, we verify using goodness-of-fit tests if the EVM margin distances (Eq. (1)) in these datasets follow the Weibull distribution (Section 3.3). Next in Section 3.4, we show that the EVM model with the Weibull model replaced by some other distributions (e.g. normal) realizes similar performance. Finally, we visually illustrate the way how the EVM and LOF form the in-distribution and out-of-distribution areas, using the CIFAR-10 dataset projected onto the 2D space of the first two PCA components. This allows us to partly explain the difference in the performance of OoD by the EVM and LOF in our experiments.

#### 3.1 Data Sets

To evaluate the OoD detection algorithms, we used two different sources of data: text documents and images.

For the text documents case, we used the corpus of articles extracted from the Polish language Wikipedia (Wiki). It consists of 9,837 documents assigned to 34 subject categories (classes). The corpus is divided into training [19] and testing [18] set. As the OoD example, we randomly selected articles from the Polish press news[25] dataset (Press).

Several approaches to represent documents by feature vectors were developed during the past years. For our study, we have the most classical one - TF-IDF[21] and one of the most recent approaches - BERT [5]. The TF-IDF uses a bag of word model[7] where a feature vector consists of a set of frequencies of words (terms). To limit the size of feature vectors, we focused only on the most frequent terms. The term frequency (TF) representation is modified by the Inverted Document Frequency (IDF)[21], giving the  $TF - IDF$  one. In performed experiments, we used single words as well as 2-, and 3-grams. The vector space was limited to 1000 terms. Moreover, the final TF-IDF vectors were L2 normalized. The most frequent terms and corresponding IDFs were set up on the training set and used for  $TF - IDF$  feature calculation for all data (i.e., training, testing, and outliers).

The second method, *BERT*[5], uses state-of-the-art deep-learning algorithms (i.e. Transformers), resulting in a context-aware language modeling approach. In this study, we used the Polbert<sup>4</sup>[16], a pre-trained BERT model for Polish. The Polbert network with additional classification layers was tuned on the Wiki data set. Only the embedding layer of the BERT was frozen. Since the Polbert is capable of analyzing up to 512 subwords, longer texts were cut-off. The closed set accuracy was 94.21% . As a feature vector (768-dimensional), we used the first (with index zero) token from the last Transformer layer (i.e., the one before the classification layers).

For the case of images, we used the CIFAR-10 database<sup>5</sup>. It contains 60,000 32x32 color images divided in 10 classes, i.e. airplane, automobile, bird, cat, deer, dog, frog, horse, ship, and truck. There are 5,000 images per class in the training set and 1,000 in the test set. The ResNet-101 [8] CNN model was trained from scratch for the classification task, and it achieved 95.15% final accuracy. The 2048-dimensional feature vectors were extracted from this model. As features, we used the output of the average global pooling layer (called "avgpool").

As out-of-distribution data, the MNIST<sup>6</sup> and the CIFAR-100<sup>7</sup> benchmark data sets were chosen. For each test in this paper, the number of OoD examples was equal to the number of images used in the CIFAR-10 test set. The MNIST dataset contains 70,000 28x28 grayscale images of handwritten digits. We transformed them into three RGB channels and added extra padding (to keep 32x32 size) to make them fit the trained CNN model. The CIFAR-100 set has 100 classes with 600 images per class. None of the CIFAR-100 classes appear in CIFAR-10.

### 3.2 Comparison of OoD Detection Methods

We compared the EVM with the LOF algorithm in the context of image and text data. Since we wanted to observe the effect of input space modifications on the quality of OoD detection, we also used the standardized versions of each data set (we used the popular z-score normalization with the mean and standard deviation for each variable estimated on the train data set).

In Table 1 we compare the AUCROC measure for the EVM and LOF method over different data sets.

Despite its theoretical justification, the EVM is clearly outperformed by the heuristic LOF algorithm in most test cases, except for the text data with BERT feature vectors.

To explain this, we verified if the theoretically-grounded Weibull distribution used in EVM is appropriate for data encountered in real OoD studies.

<sup>4</sup> <https://huggingface.co/dkleczek/bert-base-polish-cased-v1>

<sup>5</sup> <https://www.cs.toronto.edu/~kriz/cifar.html>

<sup>6</sup> <http://yann.lecun.com/exdb/mnist/>

<sup>7</sup> <https://www.cs.toronto.edu/~kriz/cifar.html>



Table 1: AUCROC for EVM and LOF over different data sets. Standardised data sets are denoted by '+stand'

Data set	EVM	LOF
Wiki.vs.Press.TF-IDF	0.792937	<b>0.827835</b>
Wiki.vs.Press.TF-IDF+stand	0.521511	<b>0.793559</b>
Wiki.vs.Press.BERT	<b>0.943888</b>	0.904297
Wiki.vs.Press.BERT+stand	<b>0.942756</b>	0.904234
CIFAR-10.vs.CIFAR-100	0.796409	<b>0.888728</b>
CIFAR10.vs.CIFAR100+stand	0.879586	<b>0.893454</b>
CIFAR10.vs.MNIST	0.897874	<b>0.984625</b>
CIFAR10.vs.MNIST+stand	0.972384	<b>0.982649</b>

### 3.3 Weibull Distribution Testing

The main theoretical assumption of the EVM is that margin distances (see section 2.3) follow the Weibull distribution. We empirically verified this by using the Kolmogorov-Smirnov goodness of fit test, with the null hypothesis that the margin distances have the Weibull distribution estimated by the EVM implementation. It is important to state that the margin distances were scaled by the implementation as mentioned in section 2.3. In table 2 we present mean p-values of Kolmogorov-Smirnov tests for all training examples in each data set. Assuming the test significance level of 5%, we conclude that the Weibull distribution is not appropriate (p-value < 5%) or marginally accepted (p-value = 0.087, Wiki.BERT data) in four out of six test cases. Clearly, the datasets with the highest p-values (ie. Wiki.BERT or CIFAR-10+stand, p-value > 5%, Weibull distribution appropriate) correspond to the OoD test cases in which EVM showed the best performance, as shown in table 1.

The detailed analysis of p-values for CIFAR-10 data set is shown on histograms in Fig. 2a and 2b. We can notice that normalization of CIFAR-10 data changes the distribution of margin distances: for a majority of training examples in the raw dataset (fig 2a), the Weibull model does not fit the data (most of p-values < 5%), whereas for standardized data (fig 2b) the Weibull model is appropriate (most of p-values > 5%). This clearly leads to improved performance of the EVM in OoD detection as shown in table 1 (AUCROC increased from 0.897 to 0.972).

This analysis proves that margin distances do not follow the Weibull distribution in many real datasets, contrary to the theoretical justification given in [20] (Theorem 2). The justification given in [20] is grounded on the Fisher-Tippett-Gnedenko (or Extreme Value) Theorem, which states that for a series of  $n$  i.i.d. random variables, their maximum  $M_n$  is asymptotically Weibull-distributed, ie. for some constants  $a_n, b_n$   $Pr(\frac{M_n - b_n}{a_n} < z) \rightarrow G(z)$  as  $n \rightarrow \infty$ , where  $G(z)$  is under some assumptions the Weibull distribution. Hence the underlying assumption needed for the margin distances (eq. 1) to follow the Weibull distribution is that



Table 2: Mean p-values from Weibull goodness-of-fit tests for different datasets

Data set	mean p-value
Wiki.TF-IDF	0.003366
Wiki.TF-IDF+stand	0.010634
Wiki.BERT	0.086883
Wiki.BERT+stand	0.111862
CIFAR-10	0.043452
CIFAR-10+stand	0.215405

they can be treated as the maximum from a series of i.i.d. random variables, which was not shown, but only postulated in [20].

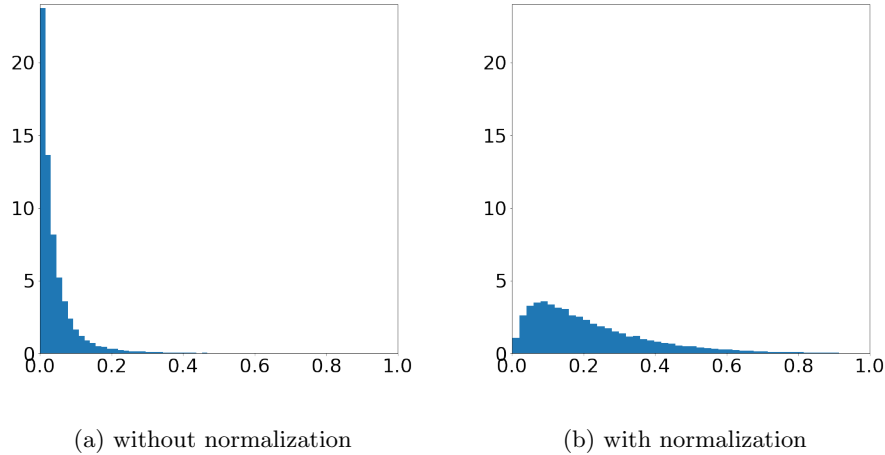


Fig. 2: Histograms of Weibull goodness-of fit test p-values for raw and standardized CIFAR-10 features.

### 3.4 EVM as a Heuristic OoD Procedure

The analysis reported in the previous section leads to the conclusion that the margin distances do not follow the Weibull distribution. Therefore, we believe that the very Weibull distribution is not the key to the EVM performance. To confirm this, we substituted the Weibull distribution by some other distributions and repeated the previous OoD detection experiments using this modified EVM. More specifically, we followed the EVM algorithm as described in the original paper [20], but fitted the parametric model directly to the margin distances ( $m_{ij}$ ,

eq. (1)), and not to the transformed  $\{\eta_{i1}, \eta_{i2}, \dots, \eta_{i\tau}\}$ . We tried four alternative CDFs: the Weibull Minimum Extreme Value (Weib min), Normal, Gamma, and empirical CDF (ECDF). The achieved AUROC values are compared with the original EVM in table 3. These results suggest that the parametric distribution type, as well as transformation applied by the libMR<sup>8</sup> have a minor influence on the EVM performance. None of the analyzed distributions clearly outperformed other models. This confirms that the assumption of the Weibull distribution is not essential for the performance of the EVM.

Table 3: AUCROC for the original EVM and its modifications based on other parametric models

Data set	EVM	Weib min	Normal	Gamma	ECDF
Wiki.vs.Press.TF-IDF	<b>0.792937</b>	0.559025	0.588428	0.761878	0.523205
Wiki.vs.Press.TF-IDF+stand	0.521511	<b>0.717006</b>	0.551327	0.673260	0.518462
Wiki.vs.Press.BERT	0.943888	0.935413	<b>0.949327</b>	0.940496	0.922417
Wiki.vs.Press.BERT+stand	0.942756	0.930245	<b>0.947738</b>	0.941205	0.920710
CIFAR-10.vs.CIFAR-100	0.796409	<b>0.887941</b>	0.828649	0.772505	0.751740
CIFAR-10.vs.CIFAR-100+stand	<b>0.879586</b>	0.832547	0.878440	0.870419	0.817091
CIFAR-10.vs.MNIST	0.897874	<b>0.957250</b>	0.926712	0.872924	0.859684
CIFAR-10.vs.MNIST+stand	0.972384	<b>0.978867</b>	0.978688	0.972445	0.971501

### 3.5 Low Dimensional Example

To illustrate the behavior of OoD methods, we performed a set of numerical experiments on CIFAR-10 images projected by PCA onto two-dimensional space. Projected images were used to build EVM and LOF models. Next, the 2D space, in the area of CIFAR-10 data values, was equally sub-sampled, forming a X-Y grid. Each of the grid points was assigned to the OoD or in-distribution class by the EVM and LOF algorithm using different values of rejection threshold, as presented in Fig. 3 and Fig. 4. The training data points are marked in colors corresponding to the original class. Black dots represent grid data marked by the corresponding algorithm as in-distributions, whereas white dots represent OoD points. Notice, that background is also white, so the area without any black dots represents OoD space.

In Fig. 3a, we can notice that the in-distribution area (black points) covers not only training data but also the area around them. So, all test examples are likely to be correctly recognized as in-distribution, but OoD examples laying between classes will be incorrectly recognized as in-distribution. Hence, the in-distribution areas (shown by black points in 3a) are apparently too wide. We can narrow them by increasing the threshold. However, as we can notice in 3a,

<sup>8</sup> <https://github.com/Vastlab/libMR>

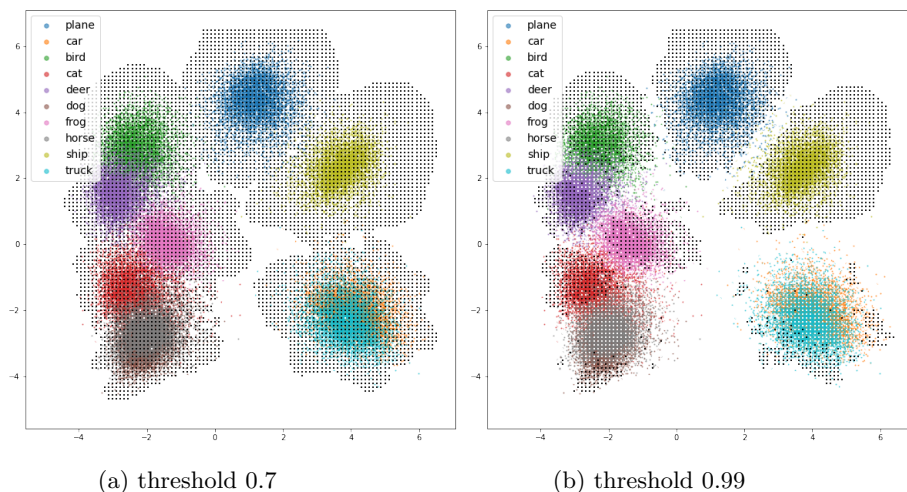


Fig. 3: OoD detection by the EVM for PCA projected CIFAR-10 data. The color points represent training data (CIFAR-10 images projected on 2D). Black points (forming an X-Y grid) are in-distribution data detected by EVM. White points (visible on colored areas, especially in picture (b)) correspond to data detected by EVM as OoD. Notice, that background is also white, so the area without any black dots is the OoD space.

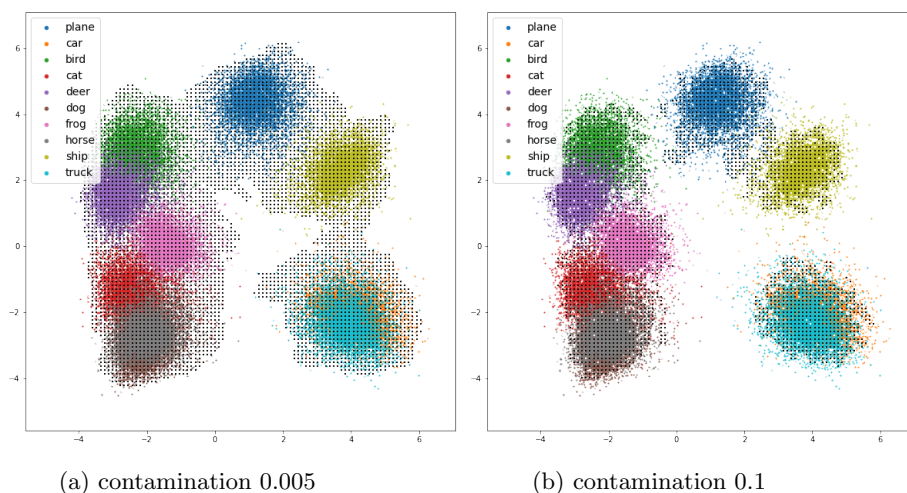


Fig. 4: OoD detection by LOF for PCA projected CIFAR-10 data. The meaning of white and black dots the same as in the previous figure.

in the case of some classes (like the plane, ship, bird, and frog), this only slightly squeezes the in-distribution areas, while in other cases (like deer and truck), training data gets marked as OoD (white dots inside gray and blue area) as OoD objects. It is an undesirable behavior of the EVM, resulting in a large number of wrong decisions. It could be noticed that such problems occur when one class is close to another, or when classes partly overlap (as cars and trucks in our example).

A similar analysis done for the LOF method (Fig. 4) does not reveal such undesirable behavior. Fig. 4a is similar to Fig. 3a. Moreover, after enlarging the contamination parameter (this results in decreasing the rejection threshold), the in-distribution areas (dark points) fit now closely to training data (Fig. 4b). However, a close look at Fig. 4a shows that LOF in-distribution areas do not extend beyond training points in directions opposite to other classes (see, for example, top of the plane class - marked by blue), contrary to directions to other classes (observe the bottom area of the 'plane' class and compare it with the area above). Such behavior is caused by the fact that LOF has no knowledge about individual classes and sees the whole training data as one 'in-distribution' set.

## 4 Conclusion

In this paper, we showed that the theoretical assumptions underlying the popular Extreme Value Machine are not fulfilled in the context of many real datasets. Inter-class distances (margin distances) in practice often do not follow the Weibull distribution, as assumed by the EVM. We compared the EVM with another popular OoD detection method - LOF and showed that EVM should not be generally considered superior to this heuristic method. Both these methods attempt to model the local similarities around the training examples as the 'in-distribution' space. However, the EVM takes into account the distances to other nearest classes, while LOF is focused only on local similarities.

Since the theoretical soundness of EVM in many real-life studies can be questioned, we argue that the method should be considered another heuristic OoD procedure.

Several data-related factors affect EVM performance. First, for high-dimensional data (the curse of dimensionality effect), the inter-class borders are sampled very roughly. (In our experiments, data dimensionality was between 768 and 2048). Secondly, the EVM builds a border between OoD space and 'in-distribution' space using the distances to the nearest points from other classes. When classes are well separated (large inter-class gap), this leads to a high probability of inclusion of out-of-distribution examples lying far from the known data. Hence, models of in-distribution areas tend to be over-extended, as compared e.g. with the LOF model.

A modification of the EVM is worth investigating, in which the models of the probability of inclusion are built using not only distances to other classes but

also in-class distances. We believe this would address some problems observed in the EVM.

## Acknowledgements

The research reported in this paper was partly sponsored by National Science Centre, Poland (grant 2016/21/B/ST6/02159).

## References

1. Amodei, D., Olah, C., Steinhardt, J., Christiano, P., Schulman, J., Mané, D.: Concrete problems in ai safety. arXiv preprint arXiv:1606.06565 (2016)
2. Bendale, A., Boulton, T.: Towards open world recognition. In: Proceedings of the IEEE conference on computer vision and pattern recognition. pp. 1893–1902 (2015)
3. Bendale, A., Boulton, T.E.: Towards open set deep networks. In: Proceedings of the IEEE conference on computer vision and pattern recognition. pp. 1563–1572 (2016)
4. Breunig, M.M., Kriegel, H.P., Ng, R.T., Sander, J.: Lof: identifying density-based local outliers. In: ACM sigmod record. vol. 29, pp. 93–104. ACM (2000)
5. Devlin, J., Chang, M.W., Lee, K., Toutanova, K.: Bert: Pre-training of deep bidirectional transformers for language understanding. arXiv preprint arXiv:1810.04805 (2018)
6. Geng, C., Huang, S.j., Chen, S.: Recent advances in open set recognition: A survey. IEEE Transactions on Pattern Analysis and Machine Intelligence (2020)
7. Harris, Z.S.: Distributional structure. Word **10**(2-3), 146–162 (1954)
8. He, K., Zhang, X., Ren, S., Sun, J.: Deep residual learning for image recognition. In: Proceedings of the IEEE conference on computer vision and pattern recognition. pp. 770–778 (2016)
9. Hendrycks, D., Gimpel, K.: A baseline for detecting misclassified and out-of-distribution examples in neural networks. arXiv preprint arXiv:1610.02136 (2016)
10. Hendrycks, D., Mazeika, M., Dietterich, T.: Deep anomaly detection with outlier exposure. arXiv preprint arXiv:1812.04606 (2018)
11. Hendrycks, D., Mazeika, M., Dietterich, T.: Deep anomaly detection with outlier exposure. Proceedings of the International Conference on Learning Representations (2019)
12. Hendrycks, D., Zhao, K., Basart, S., Steinhardt, J., Song, D.: Natural adversarial examples. arXiv preprint arXiv:1907.07174 (2019)
13. Jain, L.P., Scheirer, W.J., Boulton, T.E.: Multi-class open set recognition using probability of inclusion. In: European Conference on Computer Vision. pp. 393–409. Springer (2014)
14. Júnior, P.R.M., De Souza, R.M., Werneck, R.d.O., Stein, B.V., Pazinato, D.V., de Almeida, W.R., Penatti, O.A., Torres, R.d.S., Rocha, A.: Nearest neighbors distance ratio open-set classifier. Machine Learning **106**(3), 359–386 (2017)
15. Kamoi, R., Kobayashi, K.: Why is the mahalanobis distance effective for anomaly detection? arXiv preprint arXiv:2003.00402 (2020)
16. Kłeczek, D.: Polbert: Attacking polish nlp tasks with transformers. In: Ogrodniczuk, M., Łukasz Kobylński (eds.) Proceedings of the PolEval 2020 Workshop. pp. 79–88. Institute of Computer Science, Polish Academy of Sciences (2020)

17. Mensink, T., Verbeek, J., Perronnin, F., Csurka, G.: Distance-based image classification: Generalizing to new classes at near-zero cost. *IEEE transactions on pattern analysis and machine intelligence* **35**(11), 2624–2637 (2013)
18. Młynarczyk, K., Piasecki, M.: Wiki test - 34 categories (2015), <http://hdl.handle.net/11321/217>, CLARIN-PL digital repository
19. Młynarczyk, K., Piasecki, M.: Wiki train - 34 categories (2015), <http://hdl.handle.net/11321/222>, CLARIN-PL digital repository
20. Rudd, E.M., Jain, L.P., Scheirer, W.J., Boulton, T.E.: The extreme value machine. *IEEE transactions on pattern analysis and machine intelligence* **40**(3), 762–768 (2017)
21. Salton, G., Buckley, C.: Term-weighting approaches in automatic text retrieval. *Inf. Process. Manag.* **24**(5), 513–523 (1988). [https://doi.org/10.1016/0306-4573\(88\)90021-0](https://doi.org/10.1016/0306-4573(88)90021-0), [https://doi.org/10.1016/0306-4573\(88\)90021-0](https://doi.org/10.1016/0306-4573(88)90021-0)
22. Scheirer, W.J., Jain, L.P., Boulton, T.E.: Probability models for open set recognition. *IEEE transactions on pattern analysis and machine intelligence* **36**(11), 2317–2324 (2014)
23. Scheirer, W.J., de Rezende Rocha, A., Sapkota, A., Boulton, T.E.: Toward open set recognition. *IEEE transactions on pattern analysis and machine intelligence* **35**(7), 1757–1772 (2012)
24. Scheirer, W.J., Rocha, A., Micheals, R.J., Boulton, T.E.: Meta-recognition: The theory and practice of recognition score analysis. *IEEE transactions on pattern analysis and machine intelligence* **33**(8), 1689–1695 (2011)
25. Walkowiak, T., Malak, P.: Polish texts topic classification evaluation. In: *Proceedings of the 10th International Conference on Agents and Artificial Intelligence - Volume 2: ICAART*. pp. 515–522. INSTICC, SciTePress (2018). <https://doi.org/10.5220/0006601605150522>